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Low-pass Filter

Hans-Petter Halvorsen

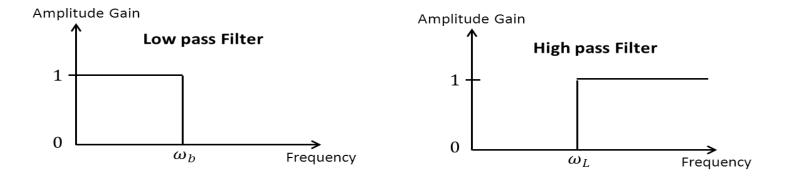
Contents

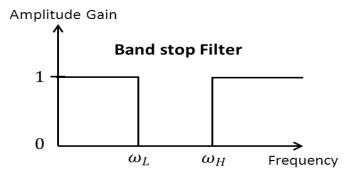
- Introduction to Filters
 - Overview of different Filters
 - What is a Low-pass Filter?
 - Why do we need a Lowpass Filter?
- Using a built-in Lowpass Filter in LabVIEW
- Create your own Lowpass Filter from scratch

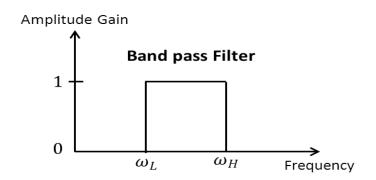
Filters

- A Filters are typically used in frequency response analysis
- A filter is used to remove given frequencies or an interval of frequencies from a signal.
- Such an application would typically be to remove noise from a signal.
- The most common is the low pass filter.
- We have 4 types of filter:
 - Low-pass Filter
 - High-pass Filter
 - Band-pass Filter
 - Band-stop Filter

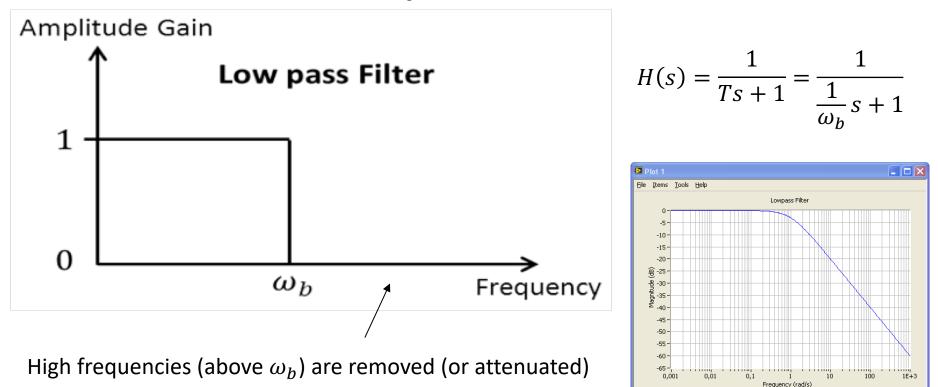
Filters







Low-pass Filter

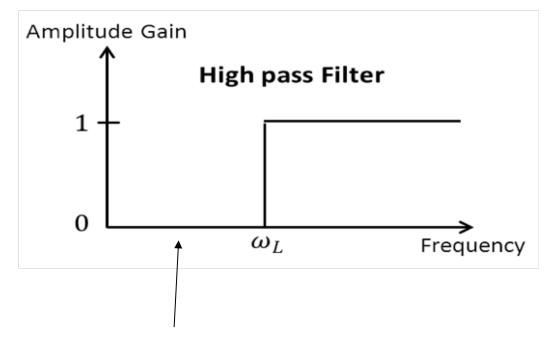


Low-pass Filter in LabVIEW

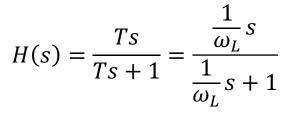
Low-pass Filter

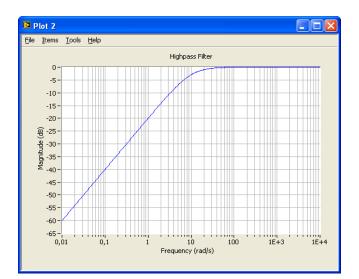
- In Measurement systems and Control Systems we typically need to deal with noise
- Noise is something we typically don't want
- Noise is high-frequency signals
- Low-pass Filters are used to remove noise from the measured signals

High-pass Filter



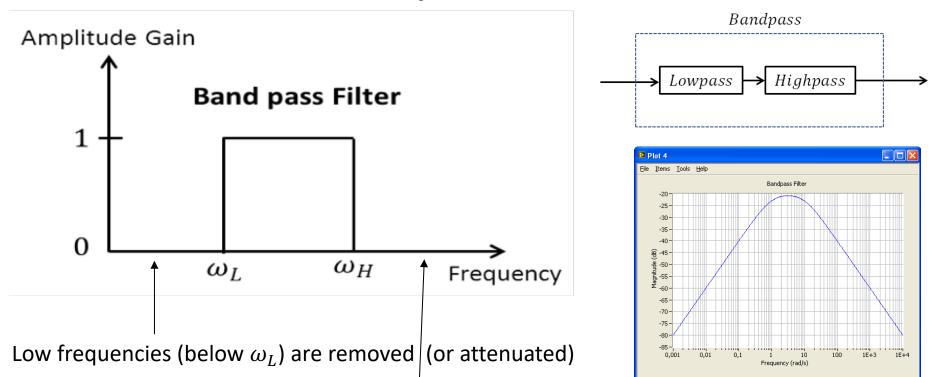
Low frequencies (below ω_b) are removed (or attenuated)





High-pass Filter in LabVIEW

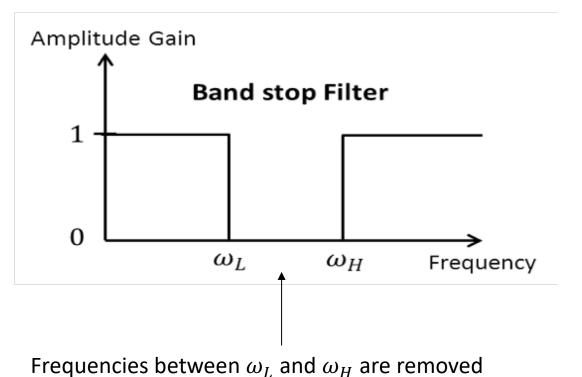
Band-pass Filter

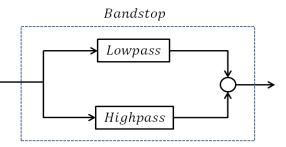


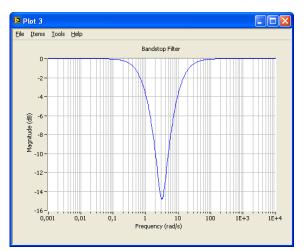
and High frequencies (above ω_H) are removed (or attenuated)

Band-pass Filter in LabVIEW

Band-stop Filter







Band-stop Filter in LabVIEW

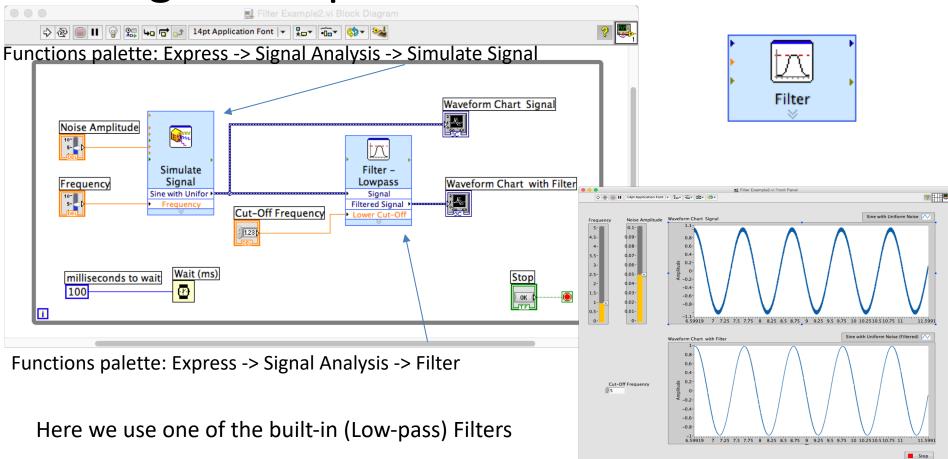
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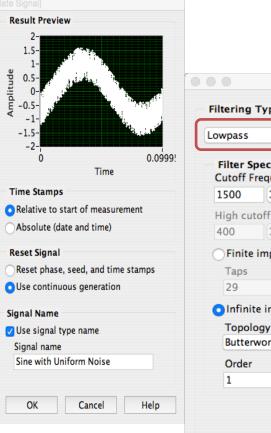
Using a built-in Low-pass Filter in LabVIEW

Hans-Petter Halvorsen

Using a Low-pass Filter to reduce Noise



Signal	Beer to a
	Result
Signal type	2-
Sine 🗘	1.5-
Frequency (Hz) Phase (deg)	1- 벌 0.5-
10.3 0	-0 it no
Amplitude Offset Duty cycle (%)	-0.5 - -0.5 - -0.5 -
1 0 50	-1-
✓ Add noise	-1.5-
Noise type	-2-
Uniform White Noise	
Noise amplitude Seed number Trials	Time St
0.6 -1 1	💿 Relativ
Timing	Absol
Samples per second (Hz)	0,10501
20000 Simulate acquisition timing	Reset S
Number of samples Run as fast as possible	Reset
2000 Vationatic	OUse co
Integer number of cycles	Signal N
Actual number of samples	🗸 Use si
2000	Signal
Actual frequency	Sine w
10.3	



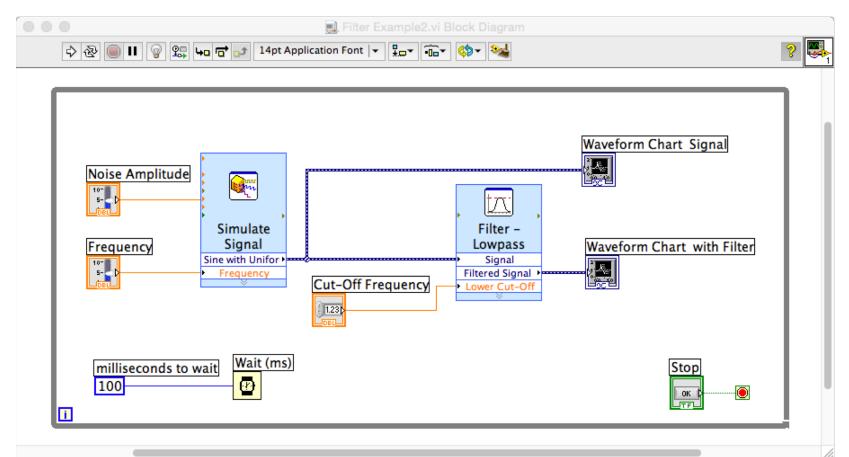
Properties

pe	Input Signal
	0.6-
	월 0.4-
ification a	-0.0 junt
i fications uency (Hz)	₩ 0-
0	-0.2-
	0 0.02 0.04 0.06 0.08 0.1
frequency (Hz)	Time
0	Result Preview
pulse response (FIR) filter	0.6-
	- 0.4- Manual Annual Annua
0	-0.4 U.2- WWW 0-
npulse response (IIR) filter	
th ᅌ	-0.2-
	0 0.02 0.04 0.06 0.08 0.1 Time
	Time
٢	View Mode
	Signals Show as spectrum
	O Transfer function
	Scale Mode
	Magnitude in dB
	Frequency in log

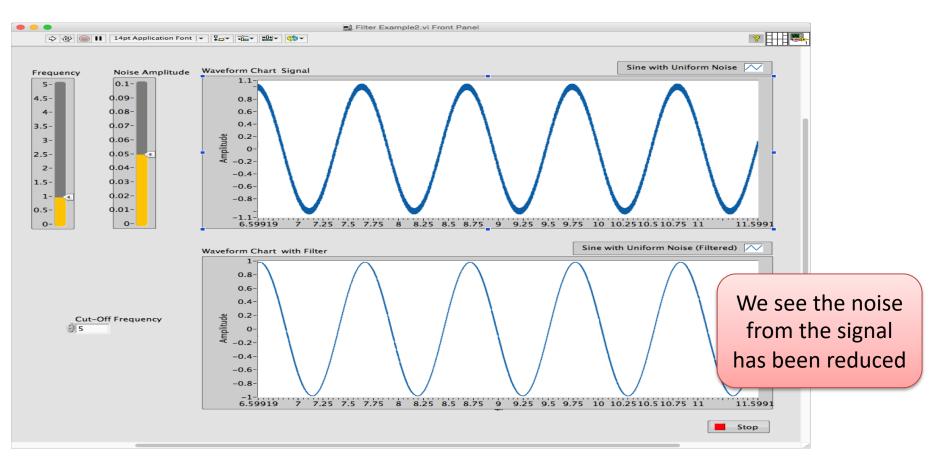
OK Cancel

Help

Using a Low-pass Filter to reduce Noise



Using a Low-pass Filter to reduce Noise



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Create your own Low-pass Filter from scratch

Hans-Petter Halvorsen

Low-pass Filter

A Low-pass Filter has the following Transfer Function:

$$H(s) = \frac{y(s)}{u(s)} = \frac{1}{T_f s + 1} \qquad \qquad u(s) \longrightarrow H(s) \longrightarrow y(s)$$

Input Unput

In LabVIEW we can implement a Low-pass Filter in many ways.

If we want to implement the Low-pass Filter in a text-based programming or using e.g., the Formula Node in LabVIEW we typically need to find a discrete version of the filter.

Low-pass Filter

A Low-pass Filter has the following Transfer Function

$$H(s) = \frac{y(s)}{u(s)} = \frac{1}{T_f s + 1}$$

We can find the Differential Equation for this filter using Inverse Laplace

We get:

$$y(s)[T_f s + 1] = u(s)$$

 $T_f y(s)s + y(s) = u(s)$

Finally we get the following differential equation:

 $T_f \dot{y} + y = u$

We apply Euler on the Differential Equation in order to find the Discrete Differential equation

Discretization of Low-pass Filter

We have the following differential equation:

 $T_f \dot{y} + y = u$

We use Euler Backward method: $\dot{x} \approx \frac{x(k)-x(k-1)}{T_c}$

Then we get:

$$T_f \frac{y(k) - y(k-1)}{T_s} + y(k) = u(k)$$

This gives:
$$y(k) = \frac{T_f}{T_f + T_s} y(k-1) + \frac{T_s}{T_f + T_s} u(k)$$

We define:

$$\frac{T_s}{T_f + T_s} \equiv a$$

This finally gives:

y(k) = (1-a)y(k-1) + au(k)

This equation can easily be implemented in LabVIEW or another programming language

Discrete Low-pass Filter Example

Lowpass Filter Transfer function:

$$H(s) = \frac{y(s)}{u(s)} = \frac{1}{T_f s + 1}$$

Inverse Laplace the differential Equation:

 $T_f \dot{y} + y = u$

We use the Euler Backward method:

$$\dot{x} = \frac{x_k - x_{k-1}}{T_s}$$

This gives:

$$T_f \frac{y_k - y_{k-1}}{T_s} + y_k = u_k$$

$$y_k = \frac{T_f}{T_f + T_s} y_{k-1} + \frac{T_s}{T_f + T_s} u_k$$

We define:

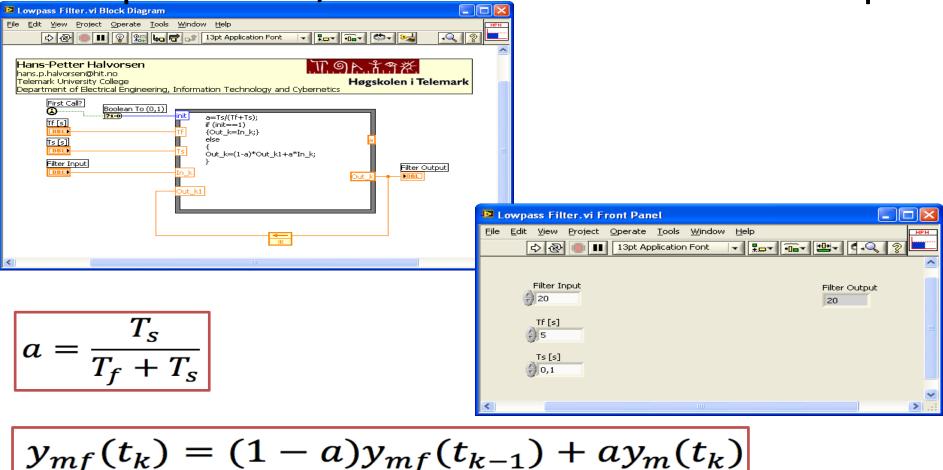
$$\frac{T_s}{T_f + T_s} \equiv a$$

This gives:

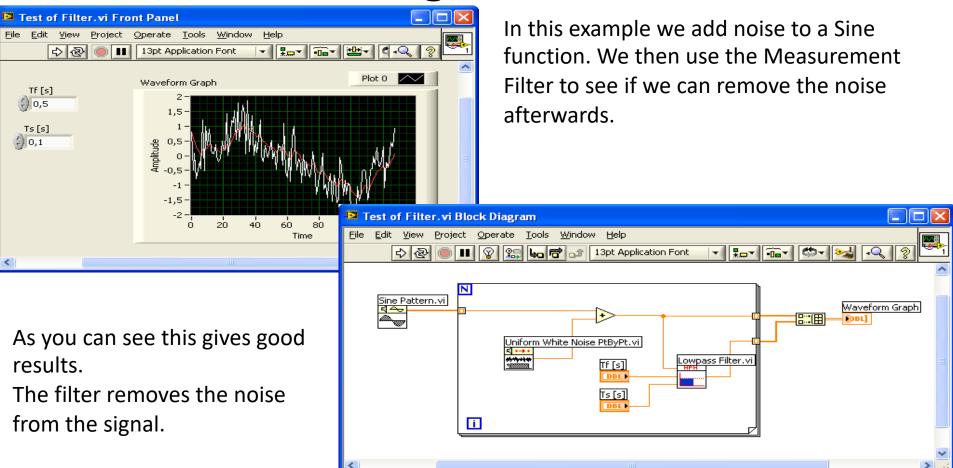
$$y_{k} = (1 - a)y_{k-1} + au_{k}$$
Filter output
Noisy input signal
$$T_{s} \leq \frac{T_{f}}{5}$$
This algorithm can be easly implemented

This algorithm can be easly implemented in a Programming language

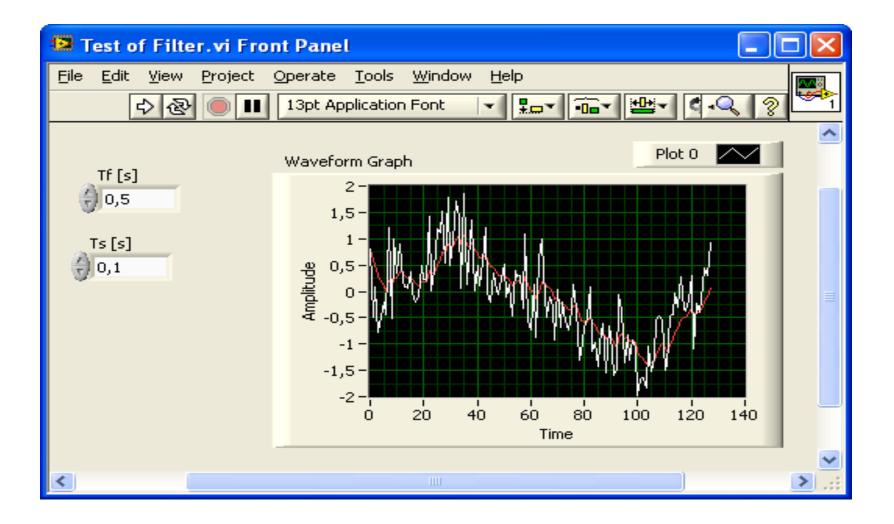
Low-pass Filter/Measurement Filter - Example

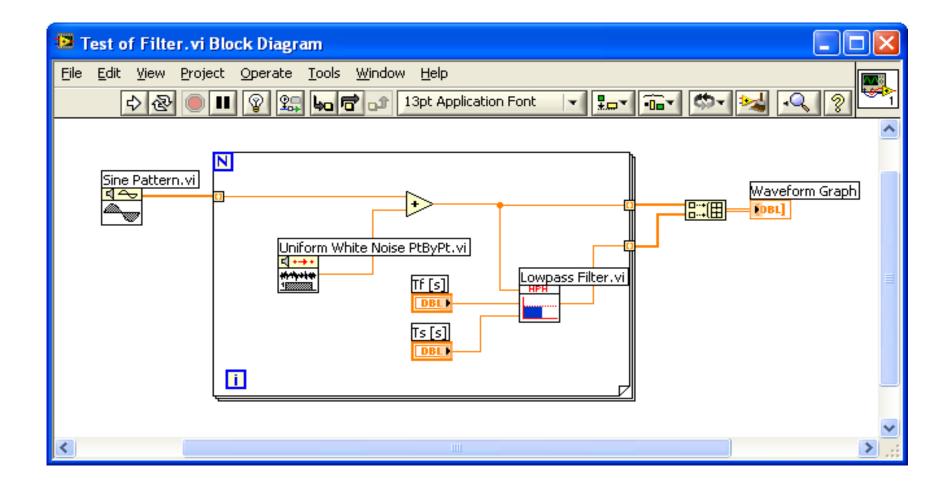


Testing the Filter



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